

# Exact Statistical Inference for Differentially Private Data

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# Differential privacy should be – and can be – modeled

- ▶ Statistical disclosure limitation mechanisms compliant with DP guarantee privacy with **provability** and **transparency**.
- ▶ Transparency enables **accurate statistical modeling** of the DP mechanism. This is the best way to ensure correctness in the resulting inference, when a (calculated) loss of statistical efficiency is present in the data.

# Differential privacy: preliminaries

## Definition (Dwork & Smith, 2009)

A random function  $\mathbf{S} : \mathcal{X} \rightarrow \mathbb{R}^p$  is  $(\epsilon, \delta)$ -differentially private if for all neighboring datasets  $\{(\mathbf{x}, \mathbf{x}') : d(\mathbf{x}, \mathbf{x}') = 1\}$  and all  $A \in \mathcal{B}(\mathbb{R}^p)$ ,

$$\Pr(\mathbf{S}(\mathbf{x}') \in A) \leq e^\epsilon \Pr(\mathbf{S}(\mathbf{x}) \in A) + \delta.$$

$\mathbf{S}$  is called  $\epsilon$ -differentially private if it is  $(\epsilon, 0)$ -differentially private.  $\epsilon$  and  $\delta$  are called the *privacy loss budget*.

## DP mechanism: output perturbation

For a dataset  $\mathbf{x} \in \mathcal{X}$  and a deterministic function  $\mathbf{s} : \mathcal{X} \rightarrow \mathbb{R}^p$ , the random function  $\mathbf{S}$  is a **perturbation mechanism** based on  $\mathbf{s}$ , if

$$\mathbf{S}(\mathbf{x}) \mid \mathbf{s}(\mathbf{x}) \sim \eta_{\text{dp}}(\cdot \mid \mathbf{s}(\mathbf{x})),$$

where  $\eta_{\text{dp}}$  is known and  $\mathbb{E}(\mathbf{S}(\mathbf{x}) \mid \mathbf{s}(\mathbf{x})) = \mathbf{s}(\mathbf{x})$ .

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where  $\eta_{\text{dp}}$  is known and  $\mathbb{E}(\mathbf{S}(\mathbf{x}) \mid \mathbf{s}(\mathbf{x})) = \mathbf{s}(\mathbf{x})$ . As a special case,  $\mathbf{S}$  is said to be an **additive perturbation mechanism** if

$$\mathbf{S}(\mathbf{x}) = \mathbf{s}(\mathbf{x}) + h\mathbf{u}.$$

- ▶  $\mathbf{u}$ : noise component with kernel density  $\eta$  and  $\mathbb{E}(\mathbf{u}) = \mathbf{0}$ , e.g. (multi-dimensional) Laplace, Normal,  $t$ , etc;
- ▶  $h = h(\epsilon, \delta, \mathbf{s}) > 0$ : bandwidth parameter chosen as a function of the privacy loss budget  $(\epsilon, \delta)$  and summary function  $\mathbf{s}(\cdot)$ .

# Private perturbation mechanisms: examples

$$\mathbf{S}(\mathbf{x}) = \mathbf{s}(\mathbf{x}) + h\mathbf{u}$$

1.  $\epsilon$ -DP Laplace mechanism (Dwork et al., 2006):
  - ▶  $\mathbf{u} \sim \text{Lap}_p(1)$ , a standard  $p$ -product Laplace,
  - ▶  $h = \epsilon^{-1}GS(\mathbf{s})$ , where  $GS(\mathbf{s})$  is the *global sensitivity* of  $\mathbf{s}$ .
2.  $(\epsilon, \delta)$ -DP Laplace mechanism (Nissim et al., 2007):
  - ▶  $\mathbf{u} \sim \text{Lap}_p(1)$ ,
  - ▶  $h = \epsilon^{-1}SS_\xi(t, \mathbf{x})$ , where  $SS_\xi(\mathbf{s}, \mathbf{x})$  is the  $\xi$ -smooth sensitivity of  $\mathbf{s}$  at  $\mathbf{x}$ ;  
 $\xi = \epsilon \{4(d + \log(2/\delta))\}^{-1} > 0$
3.  $(\epsilon, \delta)$ -DP Gaussian mechanism (Nissim et al., 2007):
  - ▶  $\mathbf{u} \sim N(\mathbf{0}, \mathbf{I}_p)$ ,
  - ▶  $h = \epsilon^{-1}5\sqrt{2\log(2/\delta)}SS_\xi(t, \mathbf{x})$ ,  $\xi = \epsilon \{4(d + \log(2/\delta))\}^{-1}$ .

## DP mechanism should not be ignored

Suppose a simple linear model between vector counts  $\mathbf{x}$  and  $\mathbf{y}$ :

$$\mathbf{y} = \beta_0 + \beta_1 \mathbf{x} + \mathbf{e}.$$

Ordinary least squares produce consistent estimators

$$\hat{\beta}_0 \longrightarrow \beta_0, \quad \hat{\beta}_1 \longrightarrow \beta_1.$$

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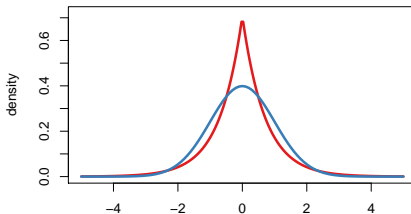
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Treating  $(\mathbf{x}, \mathbf{y})$  with  $\epsilon$ -DP mechanism,

$$\mathbf{y}_{\text{dp}} = \mathbf{y} + \mathbf{w}, \quad \mathbf{x}_{\text{dp}} = \mathbf{x} + \mathbf{z}, \quad \mathbf{w}, \mathbf{z} \sim \text{Lap}_n(\epsilon^{-1})$$

standard Normal and Laplace densities





# DP mechanism should not be ignored

Naïvely fitting the original model to differentially privatized data

$$y_{\text{dp}} = \beta_0 + \beta_1 x_{\text{dp}} + \mathbf{e},$$

the resulting least squares estimates will miss the mark:

$$\hat{\beta}_0^{\text{dp}} \approx \beta_0 + \underbrace{\alpha_{x,z}}_{\text{red}}, \quad \hat{\beta}_1^{\text{dp}} \approx \beta_1 - \underbrace{\gamma_{x,z}}_{\text{red}} \beta_1,$$

where

$$\alpha_{x,z} = \gamma_{x,z} \bar{x} + (1 - \gamma_{x,z}) \bar{z}, \quad \gamma_{x,z} = \frac{SS_{xz} + SS_z}{SS_{x+z}} \in (0, 1).$$

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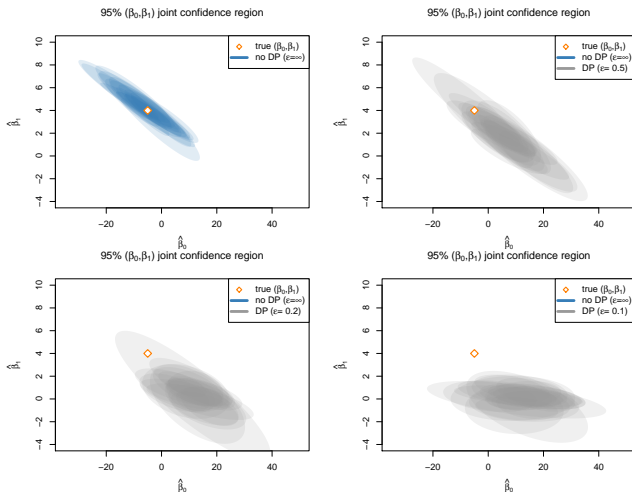
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Ignoring the DP mechanism results in misguided inference:

- ▶  $\hat{\beta}_0^{\text{dp}}, \hat{\beta}_1^{\text{dp}}$  are systematically biased;
- ▶ Strength of association between  $(\mathbf{x}, \mathbf{y})$  is underestimated (*attenuation* in the measurement error literature);
- ▶ Both estimates suffer inflated variance.



**Figure:** Naïve fitting with  $\mathbf{x}_i \sim \text{Pois}(10)$ ,  $\mathbf{y}_i = -5 + 4\mathbf{x}_i + \mathbf{e}_i$ ,  $\mathbf{e}_i \sim N(0, 5^2)$ ,  $n = 10$ , at privacy budget levels  $\epsilon = 0.5, 0.2, 0.1$ , and  $\infty$  (no privacy). Smaller  $\epsilon$  induces more misguided confidence regions for  $(\beta_0, \beta_1)$ . Each panel depicts 20 simulations.

## DP mechanism should be modeled

A model adequate for the confidential data  $\mathbf{s} = (\mathbf{x}, \mathbf{y})$ , if naïvely fitted to the privatized data  $\mathbf{s}_{\text{dp}} = (\mathbf{x}_{\text{dp}}, \mathbf{y}_{\text{dp}})$ , will almost certainly be inadequate:

$$\mathbf{y} = \beta_0 + \beta_1 \mathbf{x} + \mathbf{e} \quad \not\Rightarrow \quad \mathbf{y}_{\text{dp}} = \beta_0 + \beta_1 \mathbf{x}_{\text{dp}} + \mathbf{e}.$$

Instead, **augment** the original model with the DP mechanism:

$$\Rightarrow \quad \left( \mathbf{y}_{\text{dp}} - \mathbf{w} \right) = \beta_0 + \beta_1 \left( \mathbf{x}_{\text{dp}} - \mathbf{z} \right) + \mathbf{e}, \quad \mathbf{w}, \mathbf{z} \sim \text{Lap}(\epsilon^{-1})$$

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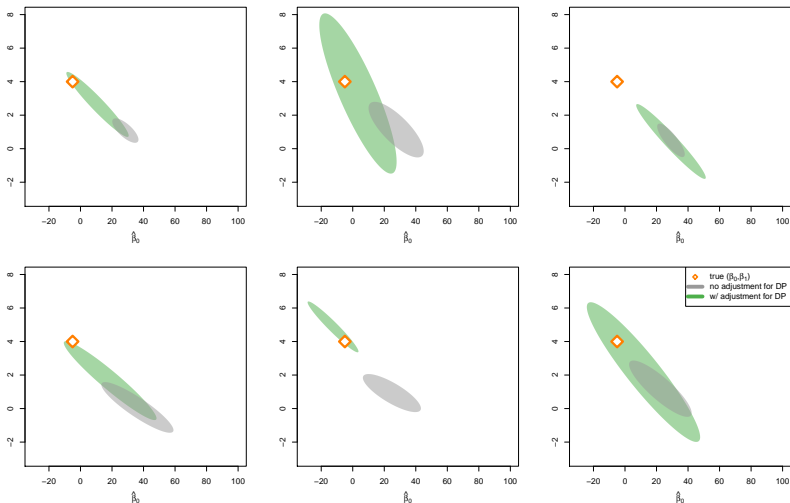
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### A general construction

Likelihood for  $\beta$  based on privatized data  $\mathbf{s}_{\text{dp}}$  (observed) is integrated over the confidential data  $\mathbf{s}$  (missing), with respect to the DP mechanism:

$$L(\beta; \mathbf{s}_{\text{dp}}) = \int \underbrace{\eta_{\text{dp}}(\mathbf{s}_{\text{dp}} | \mathbf{s})}_{\text{DP mechanism}} \underbrace{\pi(\mathbf{s} | \beta)}_{\text{original model}} \partial \mathbf{s}$$

**Transparency of the DP mechanism enables accurate modeling.**



**Figure:** Correct model (green) fitted via Monte Carlo EM (G. 2019) vs. naïve model (gray) on six instances of DP protected datasets ( $\epsilon = 0.2$ ). Displayed 95% confidence ellipses are based on normal approximations at the MLE.

# Approximate computation in Bayesian inference

A Bayesian model is posited:

- ▶ prior:  $\theta \sim \pi_0(\theta)$
- ▶ likelihood:  $\mathbf{x} \mid \theta \sim \pi(\mathbf{x} \mid \theta)$
- ▶ posterior:

$$\pi(\theta \mid \mathbf{x}) \propto \pi_0(\theta) \pi(\mathbf{x} \mid \theta)$$

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Sampling from the posterior via Monte Carlo requires that it at least can be evaluated. This is not the case for complex models.

- ▶ Case in point: intractable or implicit likelihood  $\pi(\mathbf{x} \mid \theta)$   
(e.g. the Lokta-Volterra/predator-prey model)



# A “likelihood-free” method

## ALGORITHM 1

---

Input: observed data  $\mathbf{x}_0$ , integer  $N > 0$ ;

Iterate: for  $i = 1, \dots, N$ :

    step 1, simulate  $\theta_i \sim \pi_0(\theta)$ ;

    step 2, simulate  $\mathbf{x}_i \sim \pi(\mathbf{x} \mid \theta_i)$ ;

    step 3, accept  $\theta_i$  if  $\mathbf{x}_i = \mathbf{x}_0$ , otherwise go to step 1;

Output: a set of parameter values  $\{\theta_i\}_{i=1}^N$ .

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Algorithm 1 draws  $\theta_i \sim \pi(\theta \mid \mathbf{x}_0)$ , i.i.d.

However, exact matching  $\mathbf{x}_i = \mathbf{x}_0$  may not be practical.

- ▶  $\mathbf{x}_0$  may not be discrete;
- ▶  $\mathbf{x}_0$  may be high dimensional.

# Approximate Bayesian Computation (ABC)

## ALGORITHM 2

---

Input: observed summary data  $\mathbf{s}_0 = \mathbf{s}(\mathbf{x}_0)$ , integer  $N > 0$ ,  
a kernel density  $\eta$  with bandwidth  $h > 0$ ;

Iterate: for  $i = 1, \dots, N$ :

step 1, simulate  $\theta_i \sim \pi_0(\theta)$ ;

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$\theta_i \sim \pi_{ABC}(\theta \mid \mathbf{s}_0)$  : two layers of approximation

1. From  $\pi(\theta \mid \mathbf{x}_0)$  to  $\pi(\theta \mid \mathbf{s}_0)$ : choice of  $\mathbf{s}(\cdot)$ ;
2. From  $\pi(\theta \mid \mathbf{s}_0)$  to  $\pi_{ABC}(\theta \mid \mathbf{s}_0)$ : choice of  $\eta(\cdot)$  and  $h$

# Modeling differentially private queries

The Bayesian model is modified to:

- ▶ prior:  $\theta \sim \pi_0(\theta)$
- ▶ confidential query likelihood:  $\mathbf{s} \mid \theta \sim \pi(\mathbf{s} \mid \theta)$
- ▶ privacy mechanism:  $\mathbf{s}_{\text{dp}} \mid \mathbf{s}, \theta \sim \eta_{\text{dp}}(\mathbf{s}_{\text{dp}} \mid \mathbf{s}) \quad \leftarrow \text{ignorability}$
- ▶ observed/private posterior:

$$\pi(\theta \mid \mathbf{s}_{\text{dp}}) = \frac{\pi_0(\theta) \int \eta_{\text{dp}}(\mathbf{s}_{\text{dp}} \mid \mathbf{s}) \pi(\mathbf{s} \mid \theta) d\mathbf{s}}{\int \pi_0(\theta) \int \eta_{\text{dp}}(\mathbf{s}_{\text{dp}} \mid \mathbf{s}) \pi(\mathbf{s} \mid \theta) d\mathbf{s} d\theta}.$$

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- ▶ observed/private posterior:

$$\pi(\theta \mid \mathbf{s}_{\text{dp}}) = \frac{\pi_0(\theta) \int \eta((\mathbf{s}_{\text{dp}} - \mathbf{s}) / h) \pi(\mathbf{s} \mid \theta) d\mathbf{s}}{\int \pi_0(\theta) \int \eta((\mathbf{s}_{\text{dp}} - \mathbf{s}) / h) \pi(\mathbf{s} \mid \theta) d\mathbf{s} d\theta}.$$

# ABC produces exact posterior draws for DP data

## ALGORITHM 3

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Input: private query  $\mathbf{s}_{\text{dp}} = \mathbf{S}(\mathbf{x}_0)$ , integer  $N > 0$ , perturbation mechanism w/ density  $\eta$  and bandwidth  $h(\epsilon, \delta, \mathbf{s}) > 0$ ;

Iterate: for  $i = 1, \dots, N$ :

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## Theorem (G. 2019)

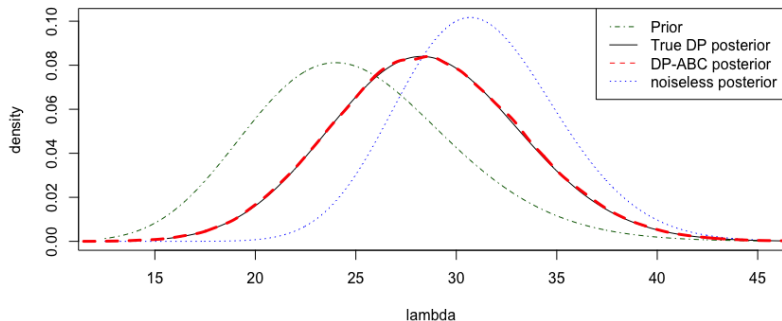
Algorithm 3 draws  $\theta_i \sim \pi(\theta \mid \mathbf{s}_{\text{dp}})$ , i.i.d.

- \* Noisy ABC (Fearnhead & Prangle, 2012);
- \* ABC under the assumption of model error (Wilkinson, 2013).

## Numerical example: privatized count data

- ▶ prior:  $\theta \sim \text{Gamma}(\alpha, \beta)$
- ▶ noiseless query likelihood:  $\mathbf{s} \mid \theta \sim \text{Pois}(\theta)$
- ▶  $\epsilon$ -Laplace privacy mechanism:  $\mathbf{s}_{\text{dp}} \mid \mathbf{s} \sim \epsilon^{-1} \text{Lap}(1)$
- ▶ Private posterior:

$$\pi(\theta \mid \mathbf{s}_{\text{dp}}) \propto \theta^{\alpha-1} e^{-(\beta+1)\theta} \left[ \frac{\Gamma(\lceil \mathbf{s}_{\text{dp}} \rceil, \theta_{\epsilon}^{+})}{\Gamma(\lceil \mathbf{s}_{\text{dp}} \rceil)} e^{\theta_{\epsilon}^{+} - \epsilon \mathbf{s}_{\text{dp}}} + \frac{\gamma(\lceil \mathbf{s}_{\text{dp}} \rceil, \theta_{\epsilon}^{-})}{\Gamma(\lceil \mathbf{s}_{\text{dp}} \rceil)} e^{\theta_{\epsilon}^{-} + \epsilon \mathbf{s}_{\text{dp}}} \right]$$



**Figure:** Algorithm 3 produces draws (red dashed density, estimated w/  $N = 10^6$ ) exactly from the true posterior (black solid density), and is different from the incorrect posterior (blue dotted density) which treats  $s_{dp} = 37.4$  as if confidential. Green dot-dash density is the prior.  $\alpha = 25, \beta = 1, \epsilon = 0.2$ .

# Exact likelihood inference with Monte Carlo EM

Expectation-Maximization (Dempster et al., 1977) in the context of differential privacy:

- ▶ complete data is  $(\mathbf{s}, \mathbf{s}_{\text{dp}})$ ;
- ▶ missing data is  $\mathbf{s}$ , where  $\mathbf{s} \mid \theta \sim \pi(\mathbf{s} \mid \theta)$ ; ← data analyst
- ▶ observed data is  $\mathbf{s}_{\text{dp}}$ , where  $\mathbf{s}_{\text{dp}} \mid \mathbf{s} \sim \eta_{\text{dp}}(\cdot \mid \mathbf{s})$ . ← data curator

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Iterate till convergence:

- E-step:

$$\begin{aligned} Q(\theta; \theta^{(t)}) &= \mathbb{E} \left( \log L(\theta; \mathbf{s}, \mathbf{s}_{\text{dp}}) \mid \mathbf{s}_{\text{dp}}, \theta^{(t)} \right) \\ &= \mathbb{E} \left( \log \pi(\mathbf{s} \mid \theta) \mid \mathbf{s}_{\text{dp}}, \theta^{(t)} \right) + \text{const.} \end{aligned}$$

- M-step:

$$\theta^{(t+1)} = \operatorname{argmax}_{\theta} Q(\theta; \theta^{(t)}).$$

# Exact likelihood inference with Monte Carlo EM

## E-STEP VIA IMPORTANCE SAMPLING

---

Iterate: for  $i = 1, \dots, N$ :

step 1, simulate  $\mathbf{s}_i \sim \pi(\mathbf{s} \mid \theta^{(t)})$ ;

← data analyst

step 2, assign weight  $\omega_i = \eta_{\text{dp}}(\mathbf{s}_{\text{dp}} \mid \mathbf{s}_i)$ ;

← data curator

Output: a set of weighted samples  $\{\mathbf{s}_i, \omega_i\}_{i=1}^N$ .

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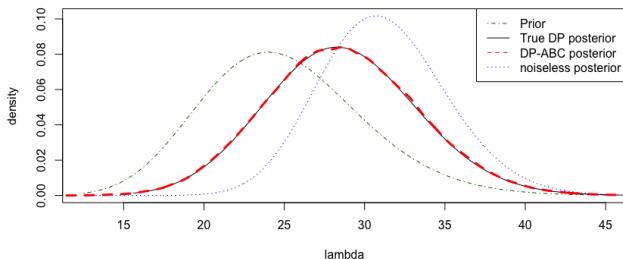
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$$\sum_{i=1}^N \omega_i b(\mathbf{s}_i) / \sum_{i=1}^N \omega_i \xrightarrow{P} \mathbb{E} \left( b(\mathbf{s}) \mid \mathbf{s}_{\text{dp}}, \theta^{(t)} \right), \quad \text{as } N \rightarrow \infty.$$

Take  $b(\mathbf{s})$  to be...

- ▶ sufficient statistic for  $\theta$ , if  $\pi(\mathbf{s} \mid \theta)$  is exponential family;
- ▶  $\log \pi(\mathbf{s} \mid \theta)$  in general;
- ▶  $\nabla_{\theta} \log \pi(\mathbf{s} \mid \theta)$  and  $\nabla_{\theta}^2 \log \pi(\mathbf{s} \mid \theta)$ , towards estimating observed score function and Fisher information.

# Numerical example revisited: privatized count data



$$\mathbf{s} \mid \theta \sim \text{Pois}(\theta), \quad \mathbf{s}_{\text{dp}} \mid \mathbf{s} \sim \epsilon^{-1} \text{Lap}(1), \quad \epsilon = 0.2, \quad \mathbf{s}_{\text{dp}} = 37.4.$$

Monte Carlo EM gives

- ▶  $\hat{\theta}_{\text{dp}} = 37.237, \hat{l}_{\text{dp}} = 1.582 \times 10^{-2};$
- ▶ Compared to incorrectly treating  $\mathbf{s}_{\text{dp}}$  as if confidential:  
 $\hat{\theta} = 37.4, \hat{l} = 2.674 \times 10^{-2} \approx 169\% \times \hat{l}_{\text{dp}}.$



## Contribution & takeaway

- ▶ Theoretically exact statistical inference for general likelihood and Bayesian models with DP data;
- ▶ Applicable to all proper Bayesian priors;
- ▶ Fully amenable to computing acceleration for specific applications.

The analogy at play here:

approximate computation on exact data



exact computation on approximate data

such that the statistical tradeoff (efficiency vs privacy) becomes aligned with the computational tradeoff (approximation vs exactness).

# Caveats & further research

1. Framework is overly general
  - ▶ Computing acceleration is possible, but requires domain knowledge;
  - ? How to afford accessible and (approximately) correct analysis tools to many DP data users?
  - ! Bias correction for popular models and code implementation
2. How to account for invariants imposed on the DP mechanism

# Bias correction: a quick remedy

Naïvely fitting the original model to privatized data

$$y_{\text{dp}} = \beta_0 + \beta_1 x_{\text{dp}} + \mathbf{e}$$

results in biased least squares estimates

$$\hat{\beta}_0^{\text{dp}} \approx \beta_0 + \underbrace{\alpha_{x,z}}_{\text{bias}} \beta_1, \quad \hat{\beta}_1^{\text{dp}} \approx \beta_1 - \underbrace{\gamma_{x,z}}_{\text{bias}} \beta_1,$$

where

$$\alpha_{x,z} = \gamma_{x,z} \bar{x} + (1 - \gamma_{x,z}) \bar{z}, \quad \gamma_{x,z} = \frac{\text{SS}_{xz} + \text{SS}_z}{\text{SS}_{x+z}} \in (0, 1).$$

- ▶ Both  $\alpha_{x,z}$  and  $\gamma_{x,z}$  can be estimated using the privatized data and knowledge of the DP mechanism.
- ▶ General bias correction strategies for measurement error models:
  - ▶ regression calibration
  - ▶ simulation extrapolation

# Imposing invariants on DP mechanisms

**Invariants** are exact statistics computed from the confidential micro-data (Ashmead et al., 2019), with which the DP releases should be congruent.

Two ways to impose a set of invariants  $\mathcal{C}$  onto a given DP mechanism  $S$ :

1. Co-processing:

$$S_{\mathcal{C}}(x) \stackrel{d}{=} S(x) \mid S(x) \in \mathcal{C}.$$

2. Post-processing:

$$\tilde{S}_{\mathcal{C}}(x) = \operatorname{argmin}_{a \in \mathcal{C}} \Delta(S(x), a),$$

for  $\Delta$  some discrepancy measure ( $L_2$ ,  $L_1$ , etc.)

## Co-processing guarantee: a result

Let  $S$  be an  $\epsilon$ -DP mechanism based on the confidential query  $s : \mathcal{X} \rightarrow \mathbb{R}^p$ .  $\mathcal{C} \in \mathcal{B}(\mathbb{R}^p)$  is a set of invariants, and  $S_{\mathcal{C}}$  a modified privatization mechanism such that

$$S_{\mathcal{C}} \stackrel{d}{=} S \mid S \in \mathcal{C}.$$

Then for all  $k$ -neighboring and  $\mathcal{C}$ -conforming pairs of datasets  $\{(x, x') : d(x, x') = k, s(x) \in \mathcal{C}, s(x') \in \mathcal{C}\}$ , and all  $A \in \mathcal{B}(\mathbb{R}^p)$ ,

$$P(S_{\mathcal{C}}(x) \in A) \leq \exp(2k\epsilon) P(S_{\mathcal{C}}(x') \in A).$$

**Caution:** Due to the constraint  $\mathcal{C}$  imposes on  $\mathcal{X}$ , neighboring dataset pairs with  $k = 1$  (original DP definition) may no longer be feasible.

**Proof:**

$$\begin{aligned} \frac{P(S_{\mathcal{C}}(x) \in A)}{P(S_{\mathcal{C}}(x') \in A)} &= \underbrace{\frac{P(S(x) \in A \cap \mathcal{C})}{P(S(x') \in A \cap \mathcal{C})}}_{\leq \exp(k\epsilon)} \cdot \underbrace{\frac{P(S(x') \in \mathcal{C})}{P(S(x) \in \mathcal{C})}}_{\leq \exp(k\epsilon)} \\ &\leq \exp(2k\epsilon). \end{aligned}$$

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## Co-processing vs. Post-processing

Suppose the confidential dataset has just two count entries:  $\mathbf{x} = (x_1, x_2)$ .  
The DP mechanism  $S(\mathbf{x}) = (s_1, s_2) = (x_1 + u_1, x_2 + u_2)$ ,  $u_i \sim \text{Lap}(\epsilon^{-1})$ .  
The invariant information is the total count  $x_1 + x_2 = n$ .

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## 1. Co-processing:

$$S_C(\mathbf{x}) \stackrel{d}{=} (x_1 + u_1, x_2 + u_2) \mid u_1 + u_2 = 0.$$

The density of  $S_C$  is

$$p(S_C(\mathbf{x}) = (s, n - s)) = \epsilon \exp\{-2\epsilon |s - x_1|\}.$$

That is, simulate  $s_1 \sim x_1 + \text{Lap}\left((2\epsilon)^{-1}\right)$  and set  $s_2 = n - s_1$ , or equivalently, simulate  $s_2 \sim x_2 + \text{Lap}\left((2\epsilon)^{-1}\right)$  and set  $s_1 = n - s_2$ .



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## 2. Post-processing ( $L_2$ ):

$$\tilde{S}_C^{L_2}(\mathbf{x}) = \operatorname{argmin}_{a \in \mathcal{C}} \|S(\mathbf{x}) - a\|_2 \stackrel{d}{=} (\bar{x} + \tilde{u}, \bar{x} - \tilde{u}),$$

where  $\tilde{u}$  is a 50%-50% mixture of:

- ▶ a Laplace distribution with scale  $(2\epsilon)^{-1}$ , and
- ▶ a signed Gamma distribution (i.e. a regular Gamma distribution times a fair random sign) with shape  $k = 2$  and scale  $(2\epsilon)^{-1}$ .

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## 3. Post-processing ( $L_1$ ):

$$\tilde{S}_{\mathcal{C}}^{L_1}(\mathbf{x}) = \operatorname{argmin}_{a \in \mathcal{C}} \|S(\mathbf{x}) - a\|_1 = (\tilde{s}, n - \tilde{s})$$

is not a unique mechanism, only having to satisfy

$$\tilde{s} \in [x_1 + \min(u_1, u_2), x_1 + \max(u_1, u_2)].$$

In particular,  $\tilde{s} = x_1 + u_1$  is always a solution, i.e. simply add  $\text{Lap}(\epsilon^{-1})$  noise to the first entry, and subtract the same amount from the second.

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Question: privacy guarantees for post-processing?

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